Datasheet, Rev. 2.1, September 2007

LED controller IC
BCR450

Small Signal Discretes

Never stop thinking

Edition 2007-09-26

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BCR450, LED controller IC

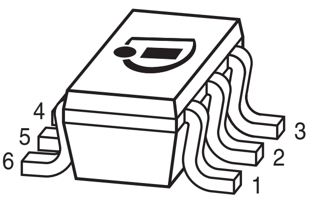
Revision History: 2007-09-26, Rev. 2.1

Previous Version: 2007-03-23, Rev. 1.0	
Page	**Subjects (major changes since last revision)**
All	Editorial changes

1 Bipolar Power LED Controller IC

Features

- Bipolar power technology
- Voltage drop across sense resistor only 0.1...0.2 V
- Maximum operating voltage: 27 V
- Over voltage protection
- Temperature shut down mechanism
- Extremely precise bandgap voltage reference
- Low shut down current < 50 nA in operating voltage range
- Maximum operating output current: 85 mA
- Maximum LED current of 2.5 A possible by using external power transistors
- Digital On/Off switch
- PWM control for LED brightness possible
- Minimum external component required (sense resistor)
- Small package: 2.9 mm x 2.5 mm x 1.1 mm (TSOP6 / SC74)



Applications

- LED controller for industrial applications, not qualified for automotive applications
- Universal constant current source
- General illumination e.g. retrofit
- Residential architectural and industrial commercial lighting for in- and outdoor
- Signal and marker lights for orientation or navigation (e.g. steps, exit ways, etc.)

2 Description

The BCR450 is a low cost LED controller IC for industrial applications realized in a bipolar IC technology. The LED Controller is capable to drive high current, high brightness LEDs up to 2.5 A by using additional external output stages as “booster“ transistors. For LED currents up to 85 mA the IC can be used as a stand alone device and requires only one voltage sense resistor as an external component

The current supply uses a sense control function with feedback mechanism that regulates the LED current.

The IC can be switched on and off by an external signal, which is also suitable to regulate brightness of the LEDs by PWM dimming. The precise internal bandgap stabilizes the circuit and provides stable current conditions over temperature range.

Furthermore, over voltage protection and temperature shut down mechanism enforce the IC to protect attached LEDs.

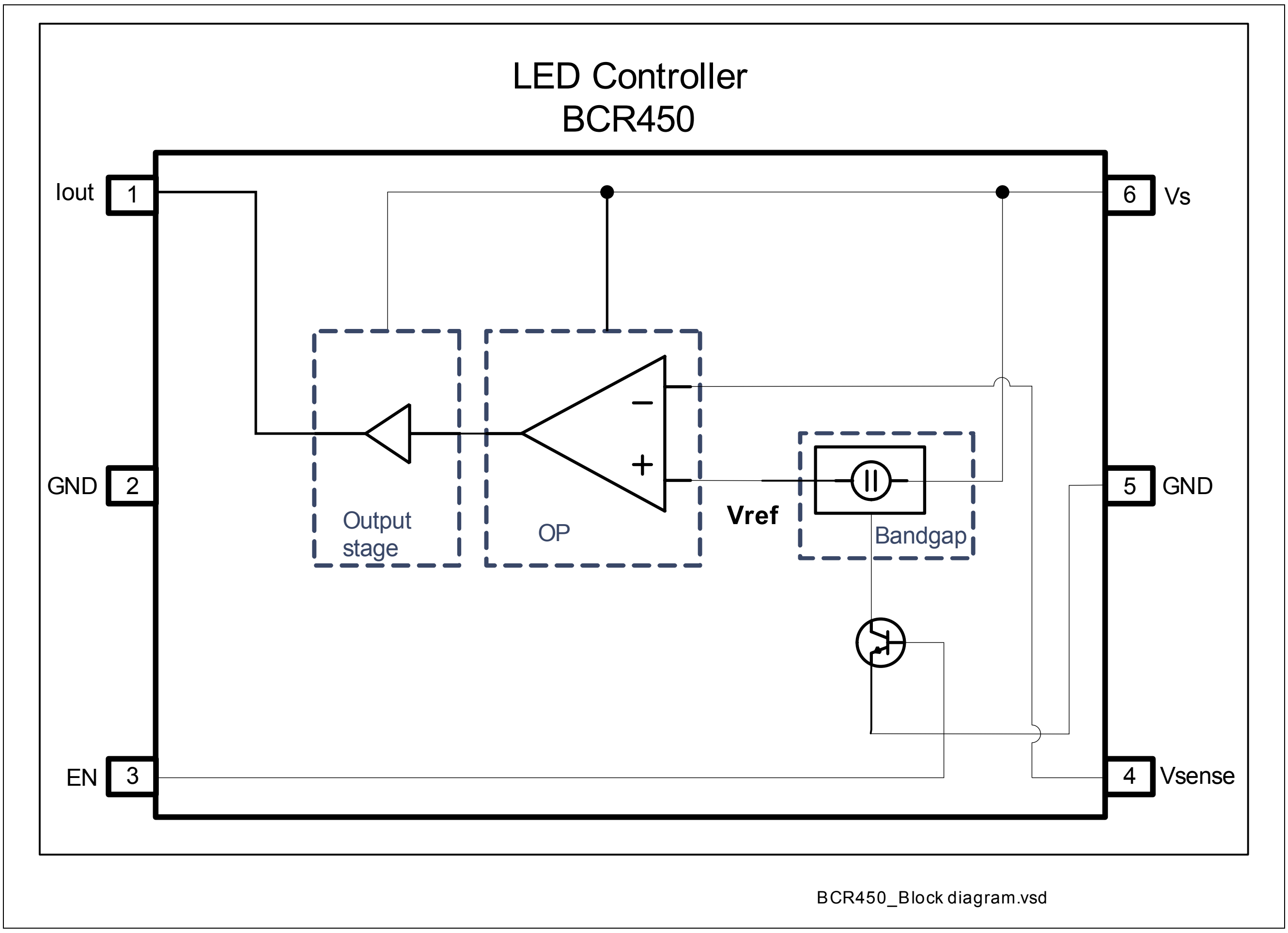


Figure 1 Block diagram

Pin Definition

Table 1 Pin definition and function

Pin number	Pin Symbol	Function
1	I_{out}	Controlled output current to drive LEDs
2	*GND*	IC ground
3	*EN*	Power On control voltage pin *(PWM input)*
4	V_{sense}	Sense control voltage pin for internal feedback mechanism
5	*GND*	IC ground
6	V_s	Supply voltage

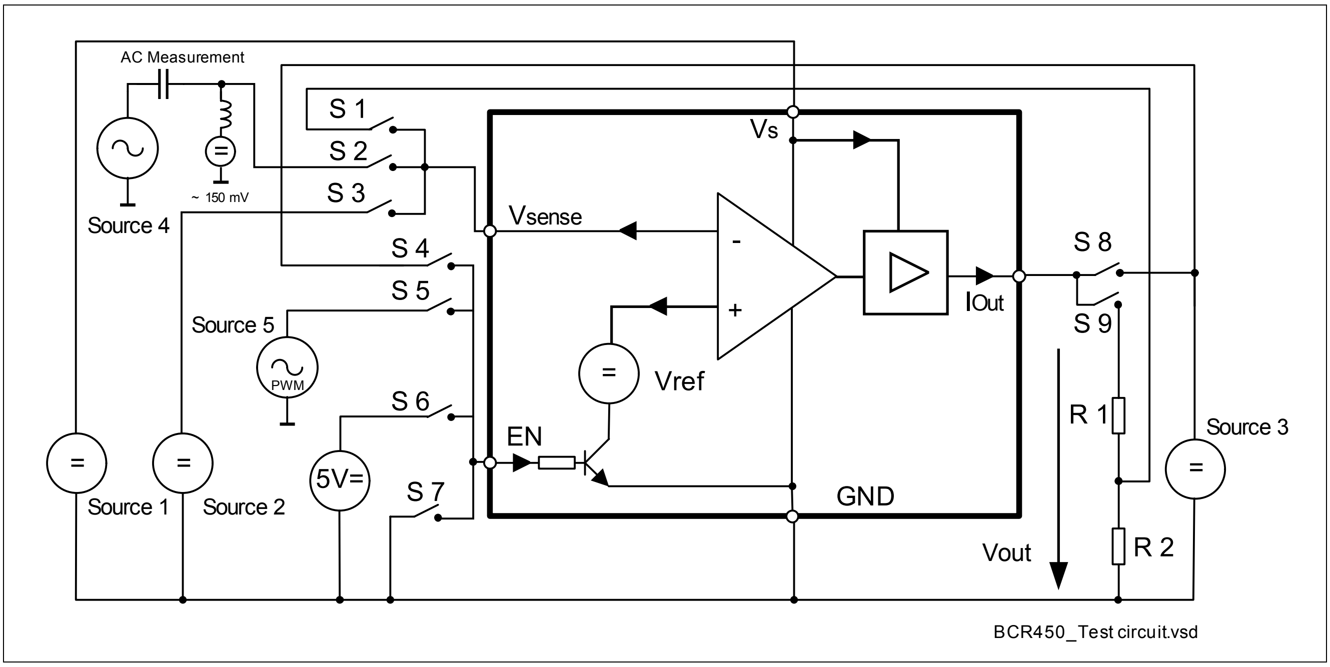


Figure 2 Electrical test circuit

Maximum Ratings

Table 2 Maximum ratings

Parameter	Symbol	Limit Value	Unit
Supply voltage	V_s	40	V
Sense Voltage	V_{sense}	200	mV
Output current	I_{out}	100	mA
Total Power Dissipation; T_s= 112.5°C	P_{tot}	500	mW
Junction temperature	T_J	150	°C
Storage temperature range	T_{STG}	-65... 150	°C
ESD capability Human Body Model[1)]	V_{ESD_HBM}	4000	V
ESD capability Machine Model[2)]	V_{ESD_MM}	400	V

1) For ESD testing, the chip was mounted in a TSOP-6 package on an application board, where GND is electrically connected to the chip GND
2) For ESD testing, the chip was mounted in a TSOP-6 package, where GND is electrically connected to the chip GND

Thermal resistance

Table 3 Thermal resistance

Parameter	Symbol	Value	Unit
Junction - solder point	R_{thJS}	75	K/W

3 Electrical Characteristics

3.1 DC Characteristics

8 V < V_S < 27 V; - 30 °C < T_J < 150 °C, all voltages with respect to ground; current directions as given in **Figure 2**; unless otherwise specified

All parameters are tested at 25 °C, unless otherwise specified

Table 4 DC Characteristics

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Overall current consumption	Is_{short}	70	90		mA	I_s short; V_s = 8 V V_{sense} = 20 mV
Overall current consumption	Is_{short}	70	90		mA	I_s short; V_s = 27 V V_{sense} = 20 mV
Overall current consumption	Is_{short}			600	µA	I_s short; V_s = 42 V V_{sense} = 20 mV
Overall current consumption open load	$Is_{open\ load}$	200	250	500	µA	I_s open load; V_s = 8 V V_{sense} = 200 mV
Overall current consumption open load	$Is_{open\ load}$	250	350	600	µA	I_s open load; V_s = 27V V_{sense} = 200 mV
Overall current consumption open load	$Is_{open\ load}$	400	450	1000	µA	I_s open load; V_s = 42V V_{sense} = 200 mV
Overall standby current consumption	$Is_{standby}$			200	nA	EN = 0 V; V_s= 8 V V_{sense} = 20 mV
Overall standby current consumption	$Is_{standby}$			200	nA	EN = 0 V; V_s = 27 V V_{sense} = 20 mV
Current of enable input	I_{EN}	20	40	70	µA	V_{sense} = 0-200 mV
Current of driver output	$I_{outhigh}$	70	90		mA	V_{sense} = 20 mV; V_s = 8 V
Current of driver output	I_{outlow}			100	nA	V_{sense} = 200 mV; V_s = 8V
Current of Sense input	I_{sense}			200	nA	V_{sense} = 20 mV
Current of Sense input	I_{sense}			100	nA	V_{sense} = 200 mV
Voltage of Driver output	V_{out}		6		V	I_{out} = 15 mA; S1, S6, S8, S9 = on; R1 = 390 Ω; R2 = 10 Ω; see **Figure 2**
Voltage of Sense input	V_{sense}	135	150	165	mV	I_{out} = 15 mA; V_s = 8 V S3, S6, S8 = on; R1 = 390 Ω;R2 = 10 Ω see **Figure 2**

Table 4 DC Characteristics (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Voltage of Sense input	V_{sense}	135	150	165	mV	I_{out} =15mA; V_s=27V S3, S6, S8 = on; R1 = 390 Ω; R2 = 10 Ω see **Figure 2**
Over voltage Protection	$V_{s, OV}$	27			V	I_{out} -> 0 A
Off- load output current	I_{CC2}	70			mA	V_{sense} = 0 V
Delta sense voltage	ΔV_{sense}	2	10	50	mV	I_{out}: 0 -> 50 mA
Lowest sufficient battery voltage overhead	V_s - V_{out}		1.2		V	I_{out} < 50 mA
Temperature shut down	Th_{TSD}	150	170	190	°C	I_{out} -> 0 A; refer to T_A

3.2 AC Characteristics

8 V < V_S < 27 V; - 30 °C < T_J < 150 °C, all voltages with respect to ground; current directions as given in **Figure 2**; unless otherwise specified

All parameters are tested at 25 °C, unless otherwise specified

Table 5 AC Characteristics [1)]

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Open Loop Gain	A_{VD}		65		dB	V_s = 8 V
	A_{VD}		70		dB	V_s = 27 V
Unity Gain Bandwidth	G_{BW}		600		kHz	V_s = 8 V
	G_{BW}		1000		kHz	V_s = 27 V
Phase Margin[2)]	PM_G		109		°	V_s = 8 V
	PM_G		102		°	V_s = 27 V

1) V_{out} = 6 V; S2, S6, S8, S9 = on; R1 = 390 Ω; R2 = 10 Ω, see **Figure 3**
2) Refer to Loop Gain

3.3 Digital Signals

All parameters are tested at 25 °C, unless otherwise specified

Table 6 Digital Control Parameter (EN)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Power on control voltage range	U_{Pon}	-0.3		5	V	
Control voltage for power on	U_{On}	0.6	0.85	5	V	
Control voltage for power off	U_{Off}	-0.3		0.35	V	
PWM signal frequency	f_{PWM}			1000	Hz	$t_{dutycycle}$ = 1%; signal level reaches 100% in on and off mode
PWM Duty cycle	$t_{dutyPWM}$	5			%	f = 5 KHz; signal level reaches 100% in on and off mode
PWM voltage	U_{PWM}			5	V	

3.4 Transient Parameters

8 V < V_S < 27 V; - 30 °C < T_J < 150 °C, all voltages with respect to ground; current directions as given in **Figure 2**; unless otherwise specified

All parameters are tested at 25 °C, unless otherwise specified

Table 7 Digital Control Parameter (EN)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Response Time	T_{ON}			10	µs	EN: 0 -> 5 V @ t_{rise} < 20ns $t_{risetime}$ @(10...90%) * V_{sense} (I_{out} ~ 15 mA);R_{sense} = 10 Ω see **Figure 4**
	T_{OFF}			70	µs	EN: 5 V -> 0 @ t_{fall} < 20 ns $t_{falltime}$ @(90...10%) * V_{sense} (I_{out} ~ 15 mA); R_{sense} = 10 Ω see **Figure 4**

3.5 AC Test Circuits

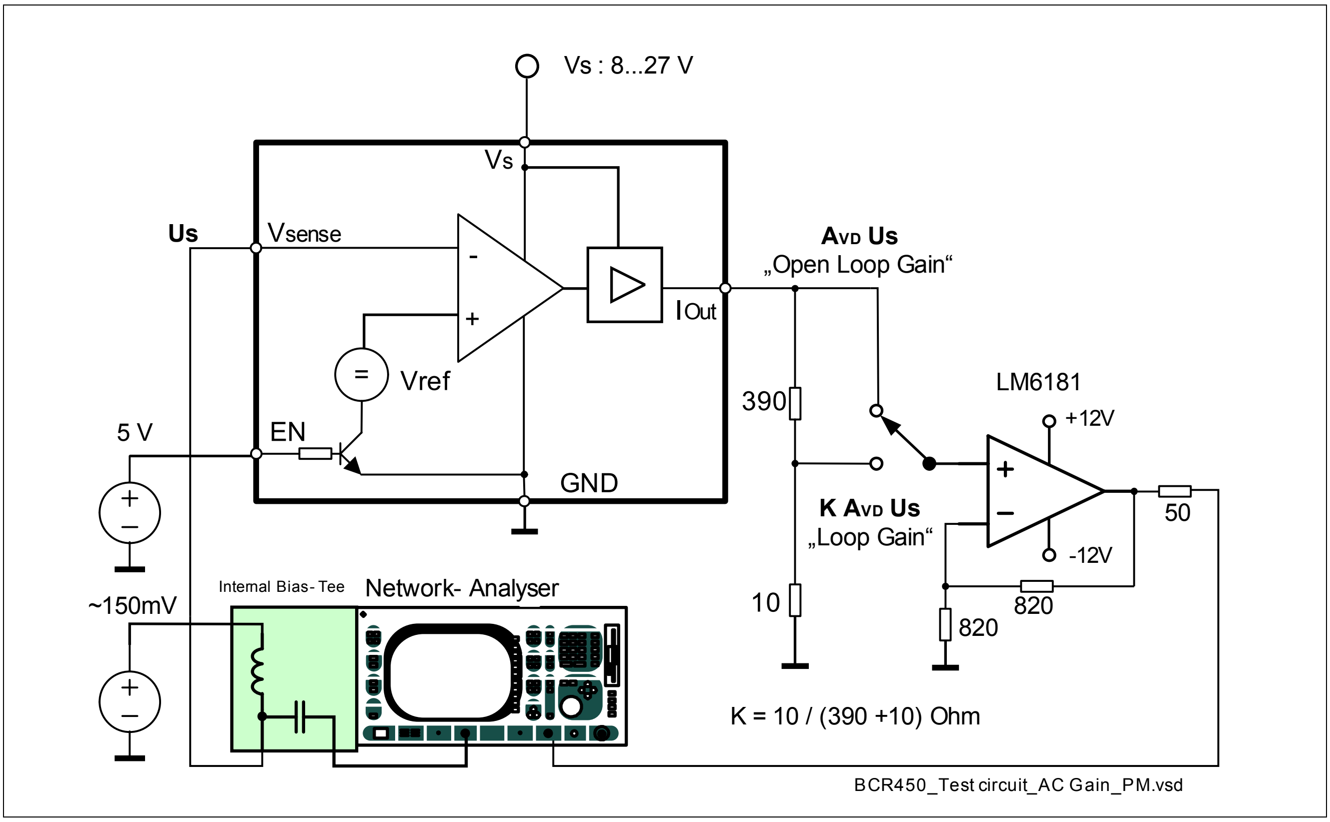


Figure 3 Electrical test circuit for open loop gain, loop gain and phase margin

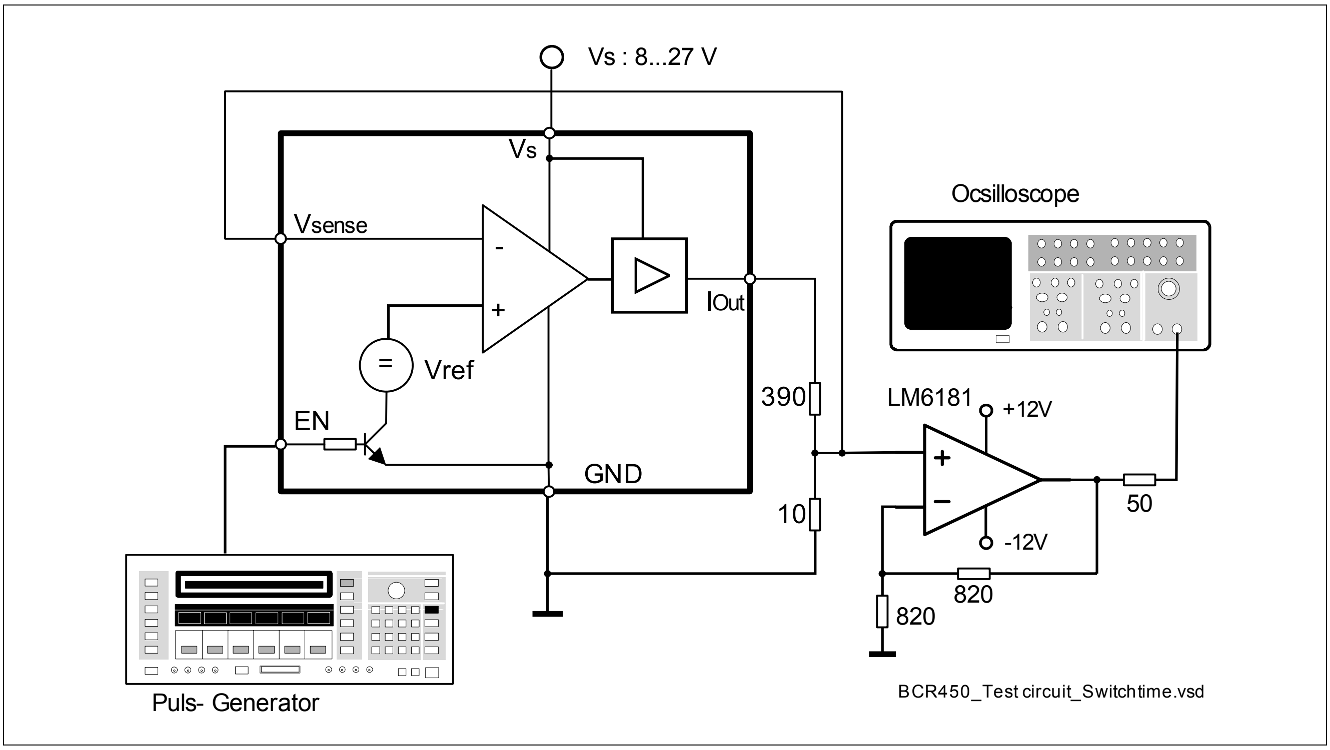


Figure 4 Electrical test circuit for response time

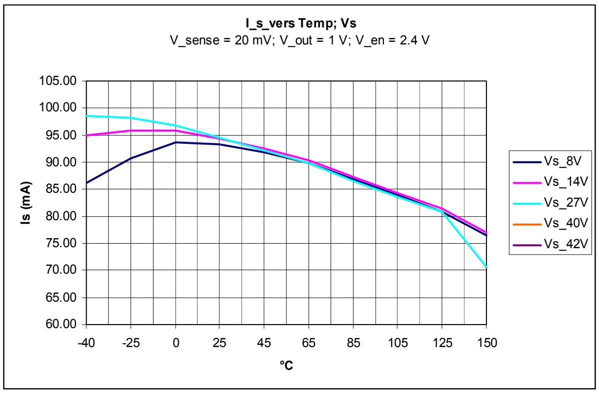
4 Measured Parameters

BCR450 IC has been measured in test bench with undefined high thermal resistance
This is valid for all diagramed DC- and AC- Parameters

4.1 DC- Parameter

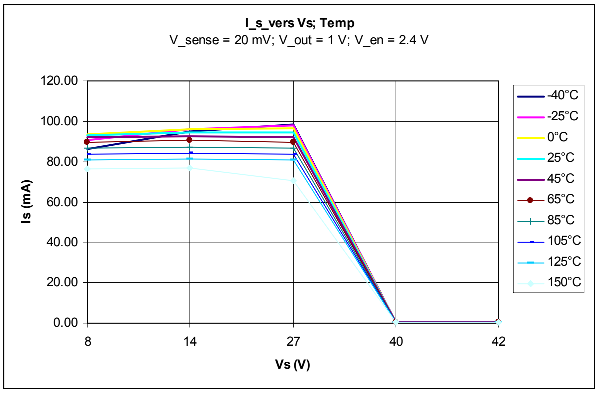
V_{out} = 1.0 V, EN = 2.4 V

I_S vers Temperature (V_S); V_{sense} = 20 mV



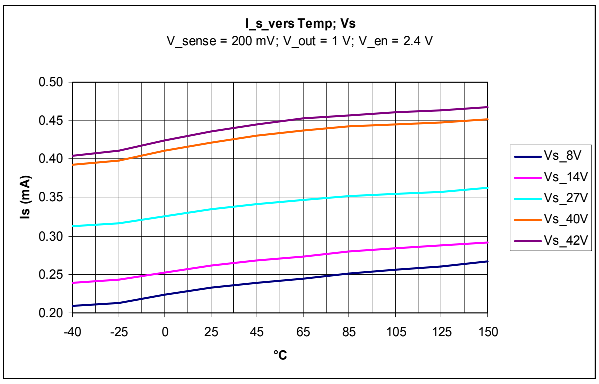
Is vers Temp_Vs_20mV_Vout1V.vsd

I_S vers V_s ($Temperature$); V_{sense} = 20 mV



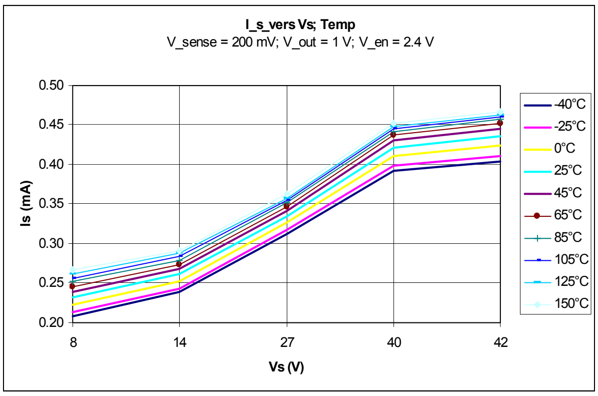
Is vers Vs_Temp_20mV_Vout1V.vsd

I_S vers Temperature (V_S); V_{sense} = 200 mV



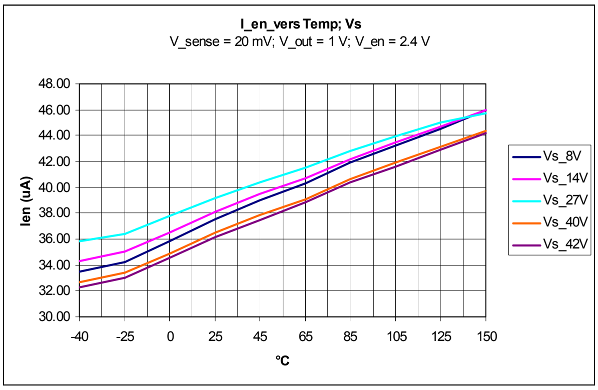
Is vers Temp_Vs_200mV_Vout1V.vsd

I_S vers V_s ($Temperature$); V_{sense} = 200 mV



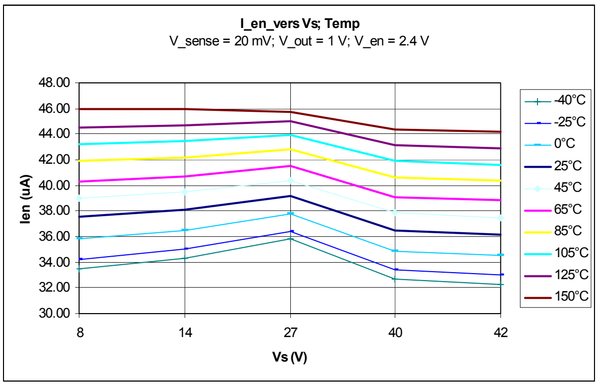
Is vers Vs_Temp_200mV_Vout1V.vsd

I_{en} vers Temperature (V_S); V_{sense} = 20 mV



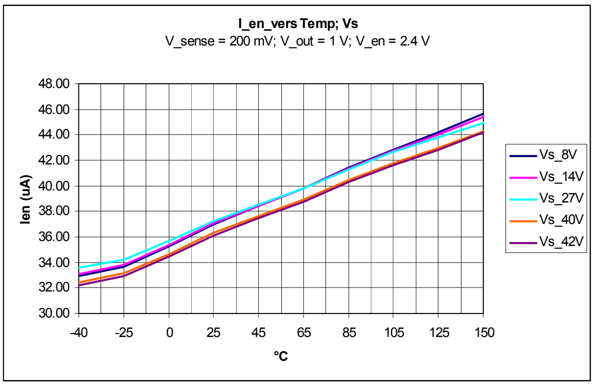
Ien vers Temp_Vs_20mV_Vout1V.vsd

I_{en} vers V_s ($Temperature$); V_{sense} = 20 mV



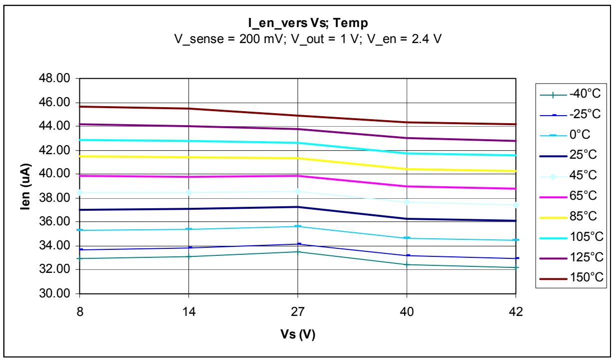
Ien vers Vs_Temp_20mV_Vout1V.vsd

I_{en} vers Temperature (V_S); V_{sense} = 200 mV



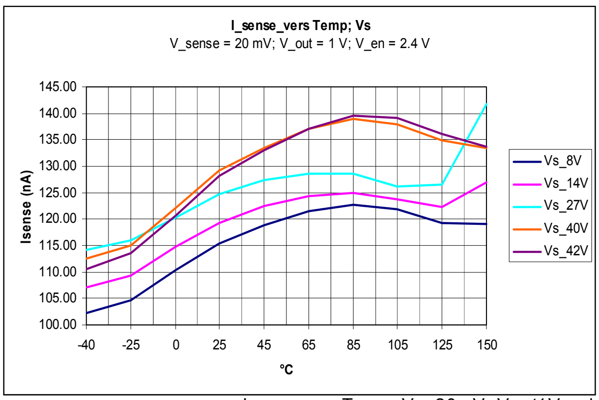
Ien vers Temp_Vs_200mV_Vout1V.vsd

I_{en} vers V_s ($Temperature$); V_{sense} = 200 mV



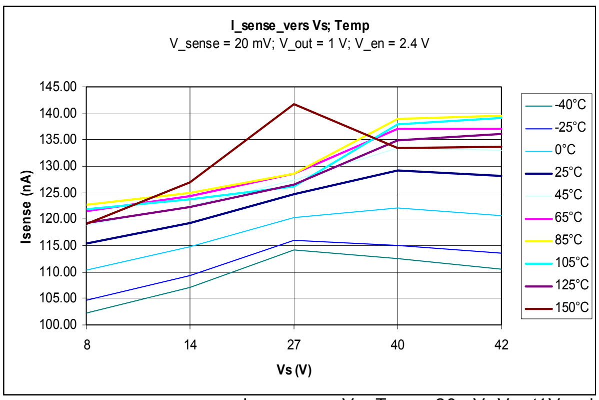
Ien vers Vs_Temp_200mV_Vout1V.vsd

I_{sense} vers Temperature (V_S); V_{sense} = 20 mV



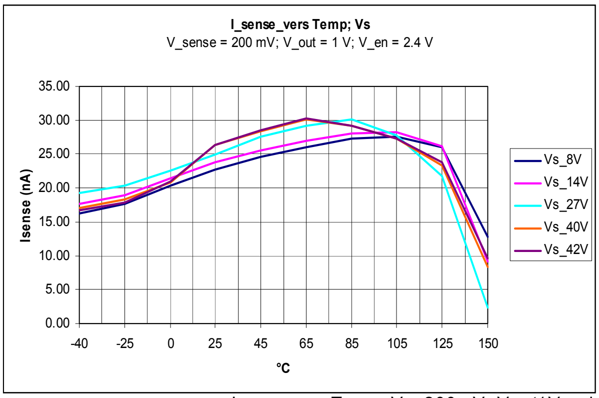
Isense vers Temp_Vs_20mV_Vout1V.vsd

I_{sense} vers V_s ($Temperature$); V_{sense} = 20 mV



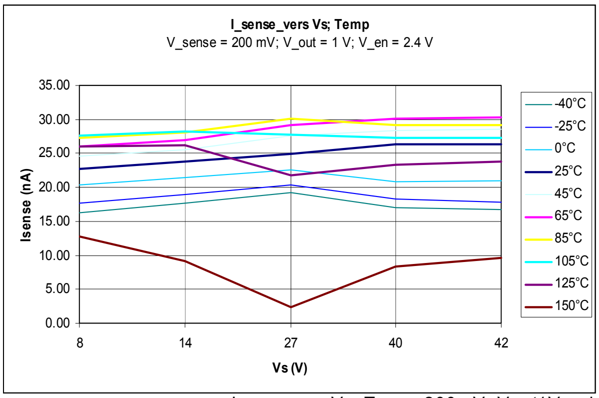
Isense vers Vs_Temp_20mV_Vout1V.vsd

I_{sense} vers Temperature (V_S); V_{sense} = 200 mV



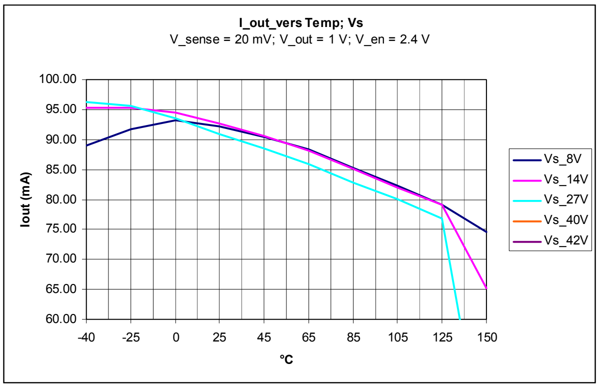
Isense vers Temp_Vs_200mV_Vout1V.vsd

I_{sense} vers V_s ($Temperature$); V_{sense} = 200 mV



Isense vers Vs_Temp_200mV_Vout1V.vsd

I_{out} vers Temperature (V_S); V_{sense} = 20 mV



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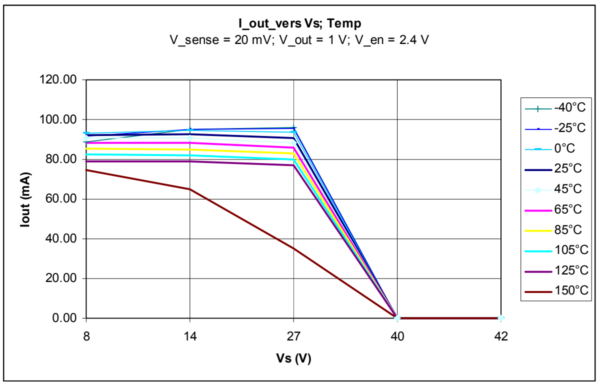
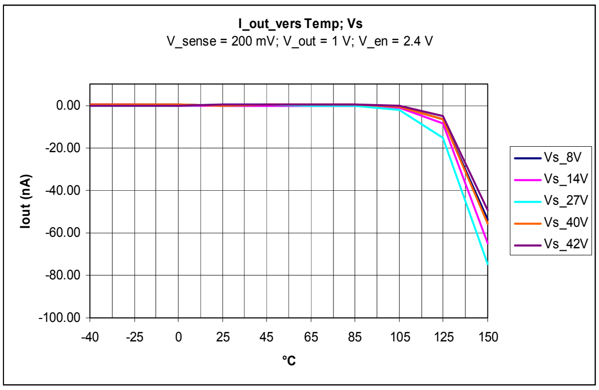
I_{out} vers V_s ($Temperature$); V_{sense} = 20 mV



I_{out} vers Temperature (V_S); V_{sense} = 200 mV



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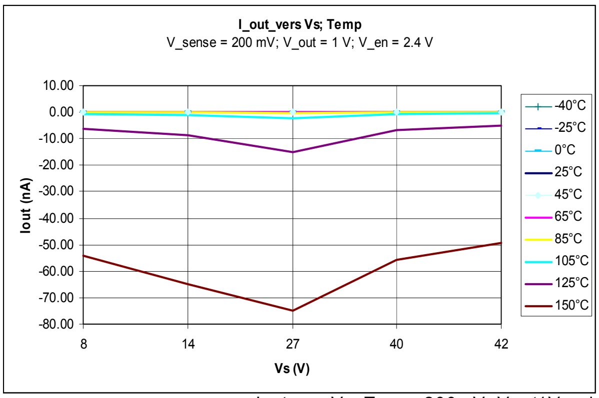
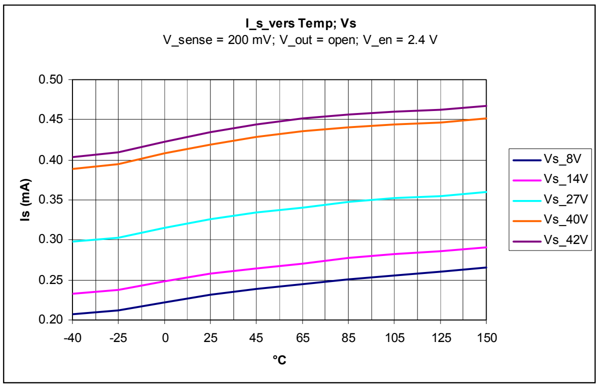
I_{out} vers V_s ($Temperature$); V_{sense} = 200 mV



Iout vers Vs_Temp_200mV_Vout1V.vsd

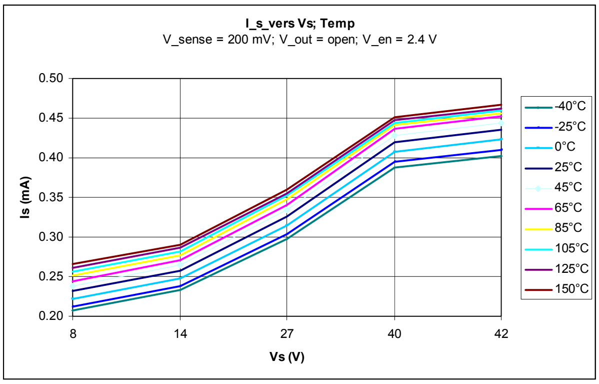
V_{out} = open, V_{sense} = 200 mV; EN = 2.4 V

I_s vers Temperature (V_S)



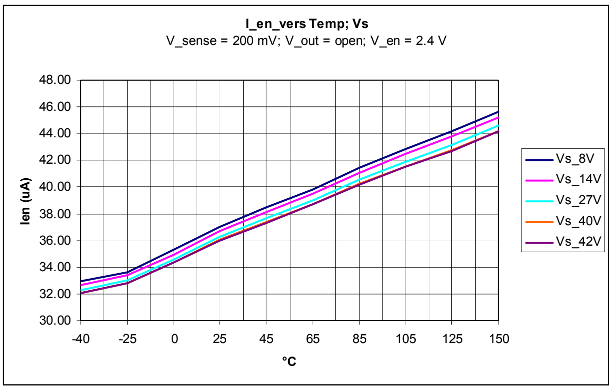
Is vers Temp_Vs_200mV_Voutopen.vsd

I_s vers V_s (*Temperature*)



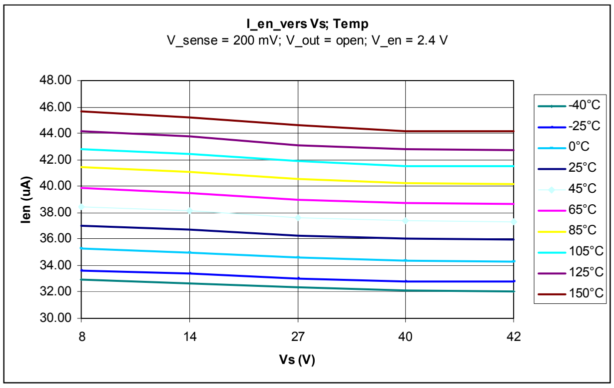
Is vers Vs_Temp_200mV_Voutopen.vsd

I_{en} vers Temperature (V_S)



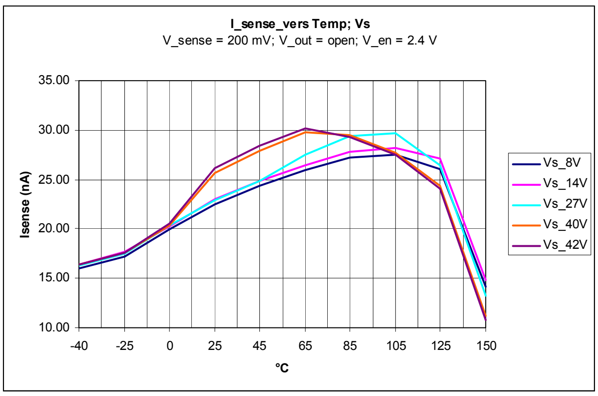
Ien vers Temp_Vs_200mV_Voutopen.vsd

I_{en} vers V_S (*Temperature*)



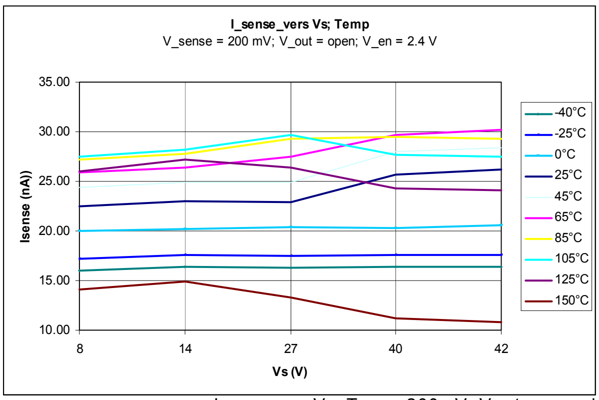
Ien vers Vs_Temp_200mV_Voutopen.vsd

I_{sense} vers Temperature (V_S)



Isense vers Temp_Vs_200mV_Voutopen.vsd

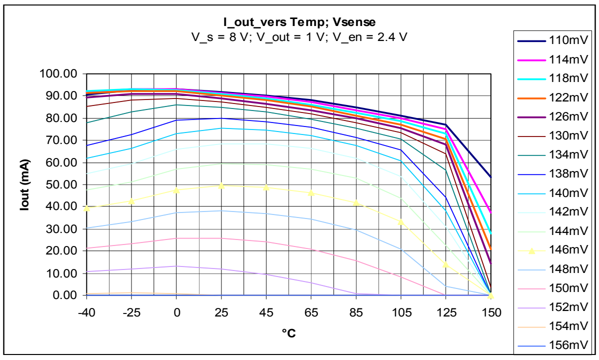
I_{sense} vers V_S (*Temperature*)



Isense vers Vs_Temp_200mV_Voutopen.vsd

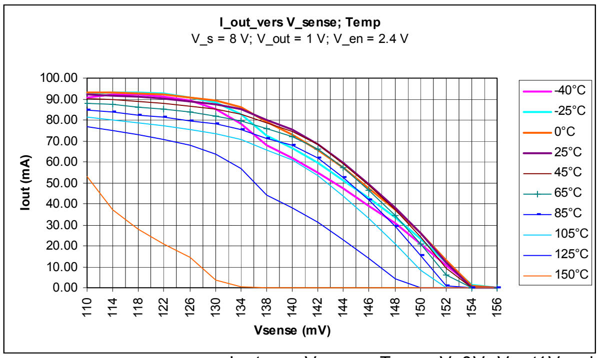
V_s = 8 V, V_{out} = 1 V; EN = 2.4 V

I_{out} vers Temperature (V_{Sense})



Iout vers Temp_Vsense_Vs8V_Vout1V.vsd

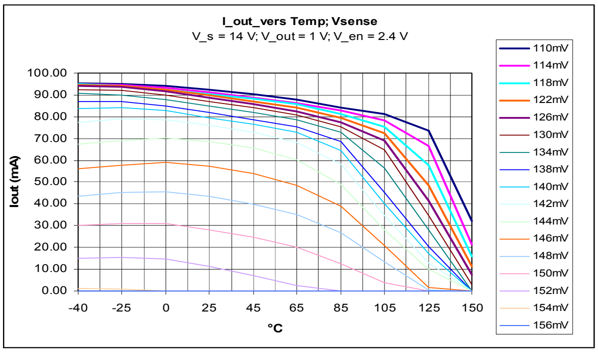
I_{out} vers V_{sense} (*Temperature*)



Iout vers Vsense_Temp_Vs8V_Vout1V.vsd

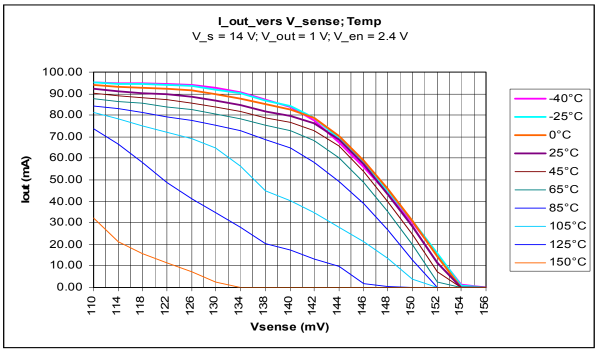
V_s = 14 V, V_{out} = 1 V; EN = 2.4 V

I_{out} vers Temperature (V_{Sense})



Iout vers Temp_Vsense_Vs14V_Vout1V.vsd

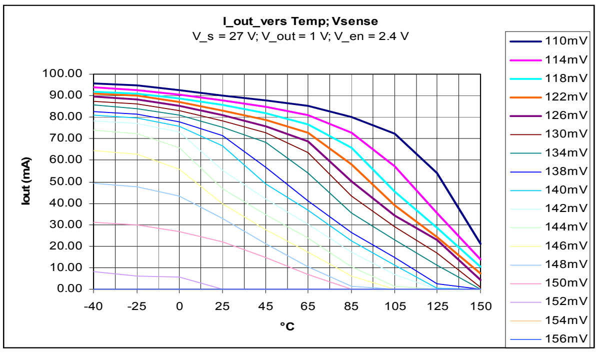
I_{out} vers V_{sense} (*Temperature*)



Iout vers Vsense_Temp_Vs14V_Vout1V.vsd

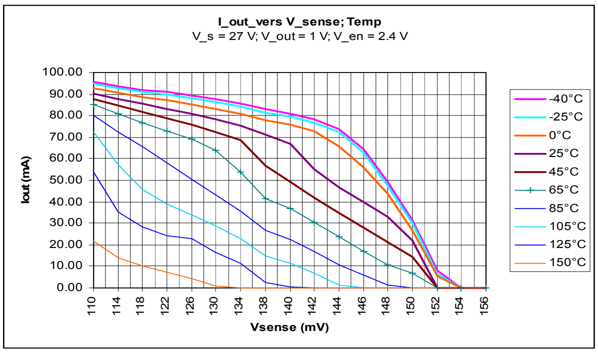
V_s = 27 V, V_{out} = 1 V; EN = 2.4 V

I_{out} vers Temperature (V_{Sense})



Iout vers Temp_Vsense_Vs27V_Vout1V.vsd

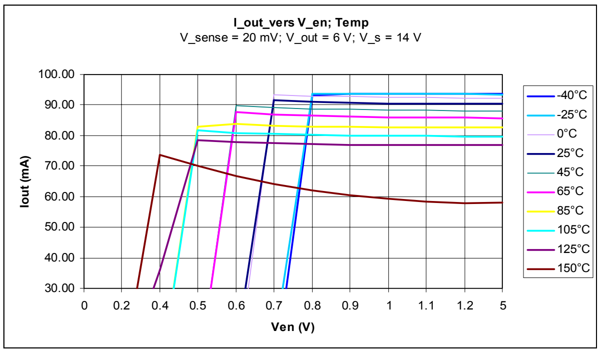
I_{out} vers V_{sense} (*Temperature*)



Iout vers Vsense_Temp_Vs27V_Vout1V.vsd

V_s = 14 V, V_{out} = 6 V; EN = 20 mV

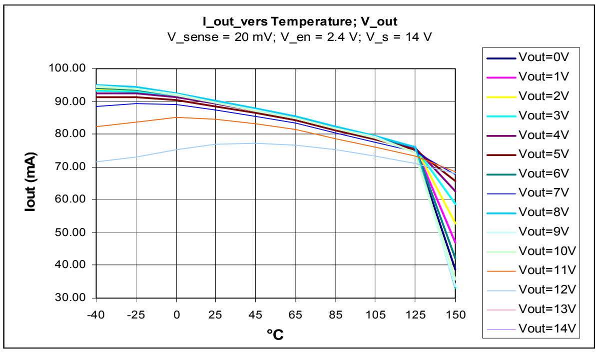
I_{out} vers EN (*Temperature*)



Iout vers Ven_Vsense20mV_Vs14V_Vout6V.vsd

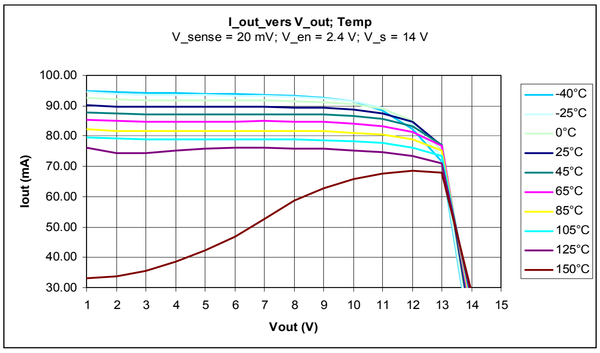
V_s = 14 V, V_{sense} = 20 mV; EN = 2.4 V

I_{out} vers Temperature (V_{out})



Iout vers Temp_Vout_Vsense20mV_Vs14V.vsd

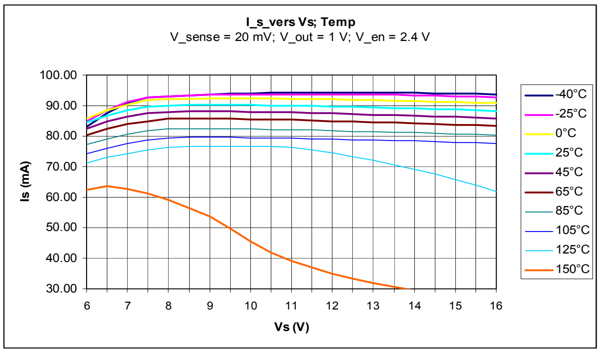
I_{out} vers V_{out} (*Temperature*)



Iout vers Vout_Vsense20mV_Vs14V.vsd

V_{out} = 1 V, V_{sense} = 20 mV; EN = 2.4 V

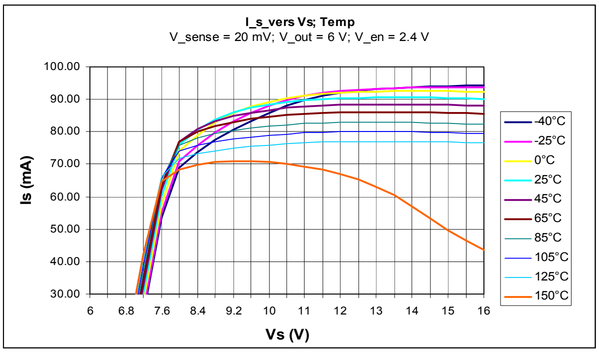
I_s vers V_S (*Temperature*)



Is vers Vs_Temp_20mV_Vout1V_entire range.vsd

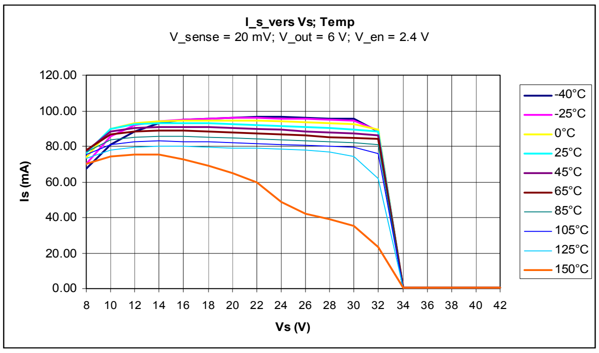
V_{out} = 6 V, V_{sense} = 20 mV; EN = 2.4 V

I_s vers V_S ($Temperature$)



Is vers Vs_Temp_20mV_Vout6V.vsd

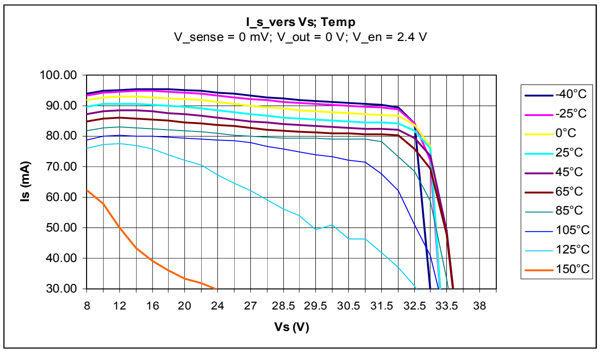
I_s vers V_S ($Temperature$)



Is vers Vs_Temp_20mV_Vout6V_entire range.vsd

$I_{s\ short}$ -> V_{out} = 0 V, V_{sense} = 0 mV; EN = 2.4 V

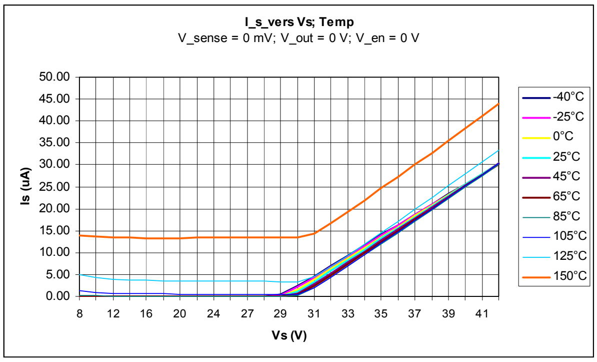
I_s vers V_S ($Temperature$)



Is vers Vs_Temp_0mV_Vout0V.vsd

$I_{s\ standby}$ -> V_{out} = 0 V, V_{sense} = 0 mV; EN = 0 V

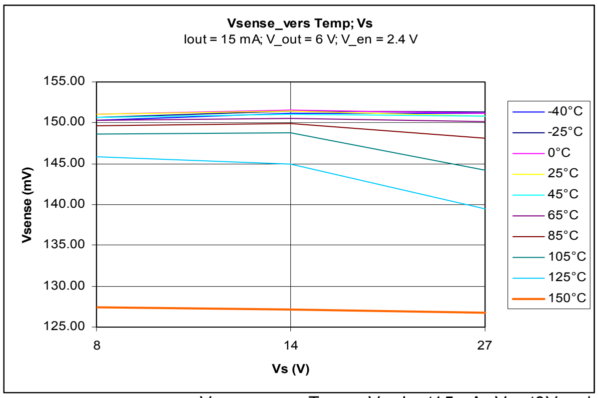
I_s vers V_S ($Temperature$)



Is vers Vs_Temp_0mV_Vout0V_EN0V.vsd

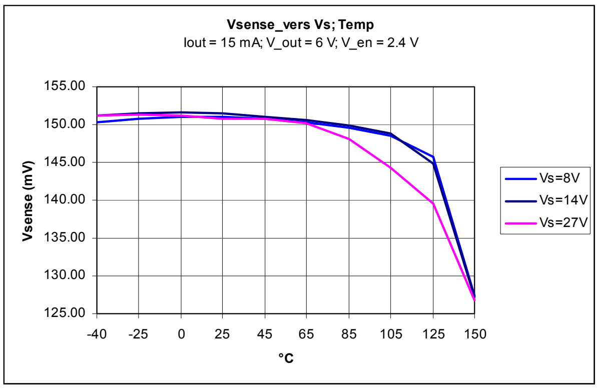
V_{out} = 6 V, I_{out} = 15 mA; EN = 2.4 V

V_{sense} vers Temperature (V_s)



Vsense vers Temp_Vs_Iout15mA_Vout6V.vsd

V_{sense} vers V_S ($Temperature$)

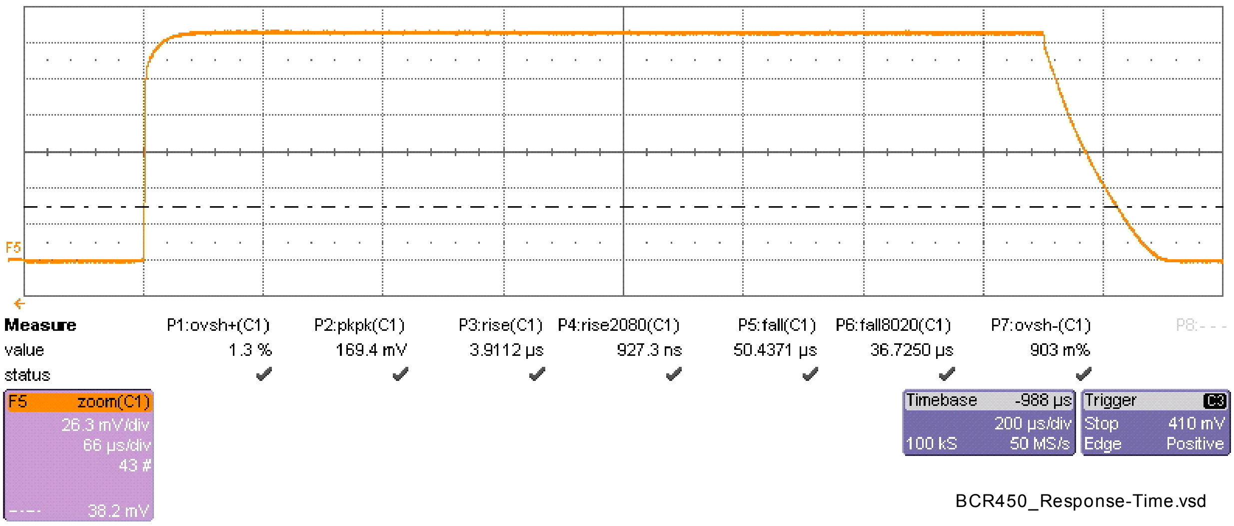


Vsense vers Vs_Temp_Iout15mA_Vout6V.vsd

4.2 AC- Parameter

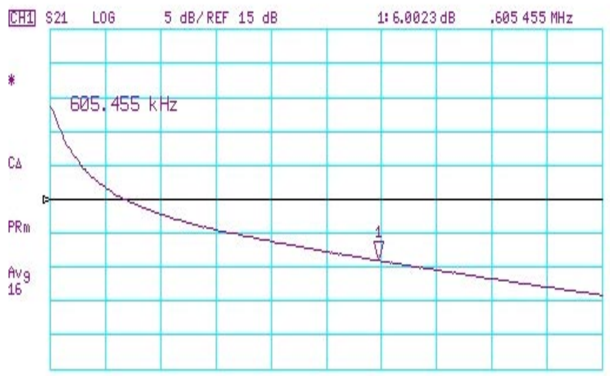
Response Time

T_{on} & T_{off}; V_s= 12 V; f_{Pulse}= 1KHz; t_{duty}=50%



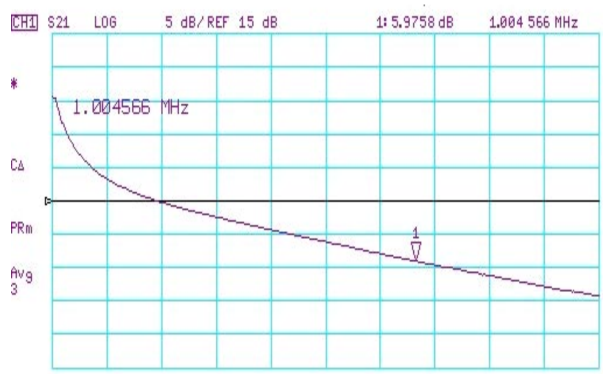
BCR450_Response-Time.vsd

Unity Gain Bandwidth G_{BW}; V_s = 8 V[1)]



BCR450_GBW_8V.vsd

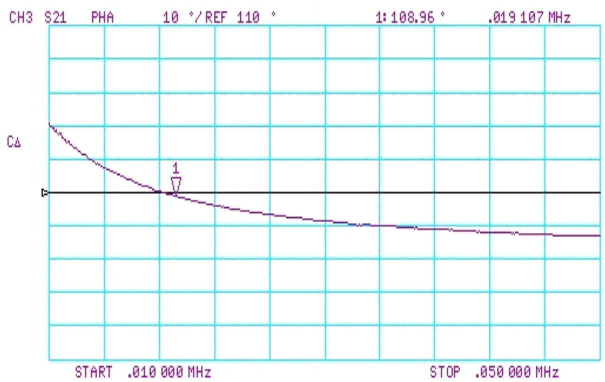
Unity Gain Bandwidth G_{BW}; V_s = 27 V



Bcr450_gbw_27v.vsd

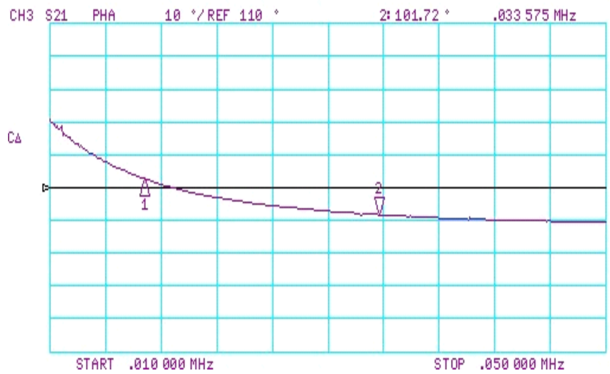
1) Marker read out at 6 dB due to the highohmic load of the operational amplifier, NWA is calibrated with 50 Ohm

Phase Margin PM_G; V_s = 8 V



Bcr450_PMg_8v.vsd

Phase Margin PM_G; V_s = 27 V



Bcr450_PMg_27v.vsd

5 Evaluation Board

The evaluation board is designed to test the BCR450 as a stand alone device for lower LED current applications and also with additional external “booster“ transistors for high current, high brightness LEDs. Up to three external transistors BCX68 or BC817SU each could be used on the PCB to minimize thermal problems.
3 LEDs in series for high current mode or 3 LEDs for low current applications can be chosen by setting resistors (see Figure 4). The particular sense voltage can be derived by jumpers which are provided in the layout for each test case. Additional test circuit is included to measure AC characteristics, and the ENABLE input is designed to connect a PWM signal. The PCB is manufactured in double sided FR4 with substrate thickness of 1.0 mm.

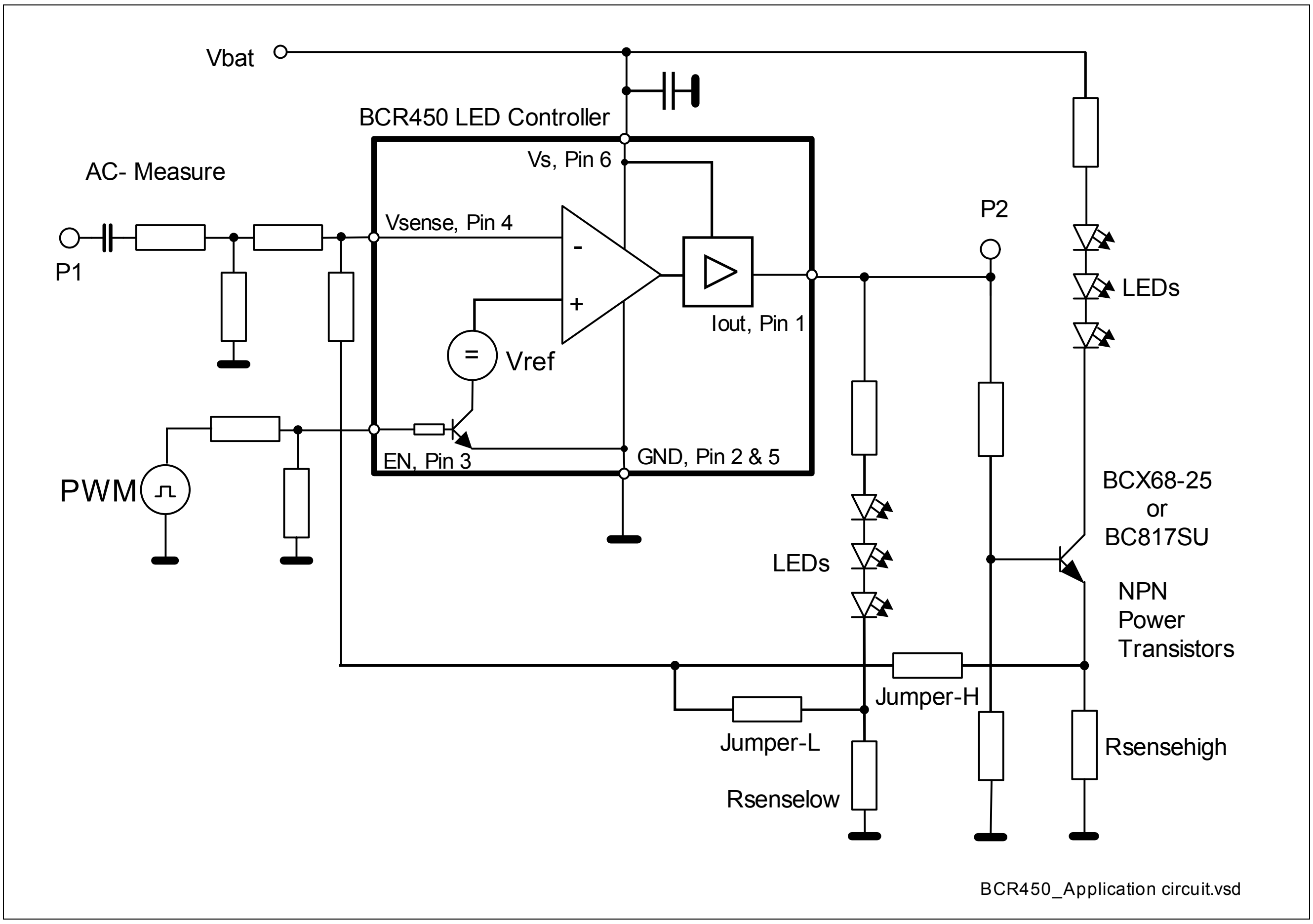


Figure 5 Evaluation board schematic

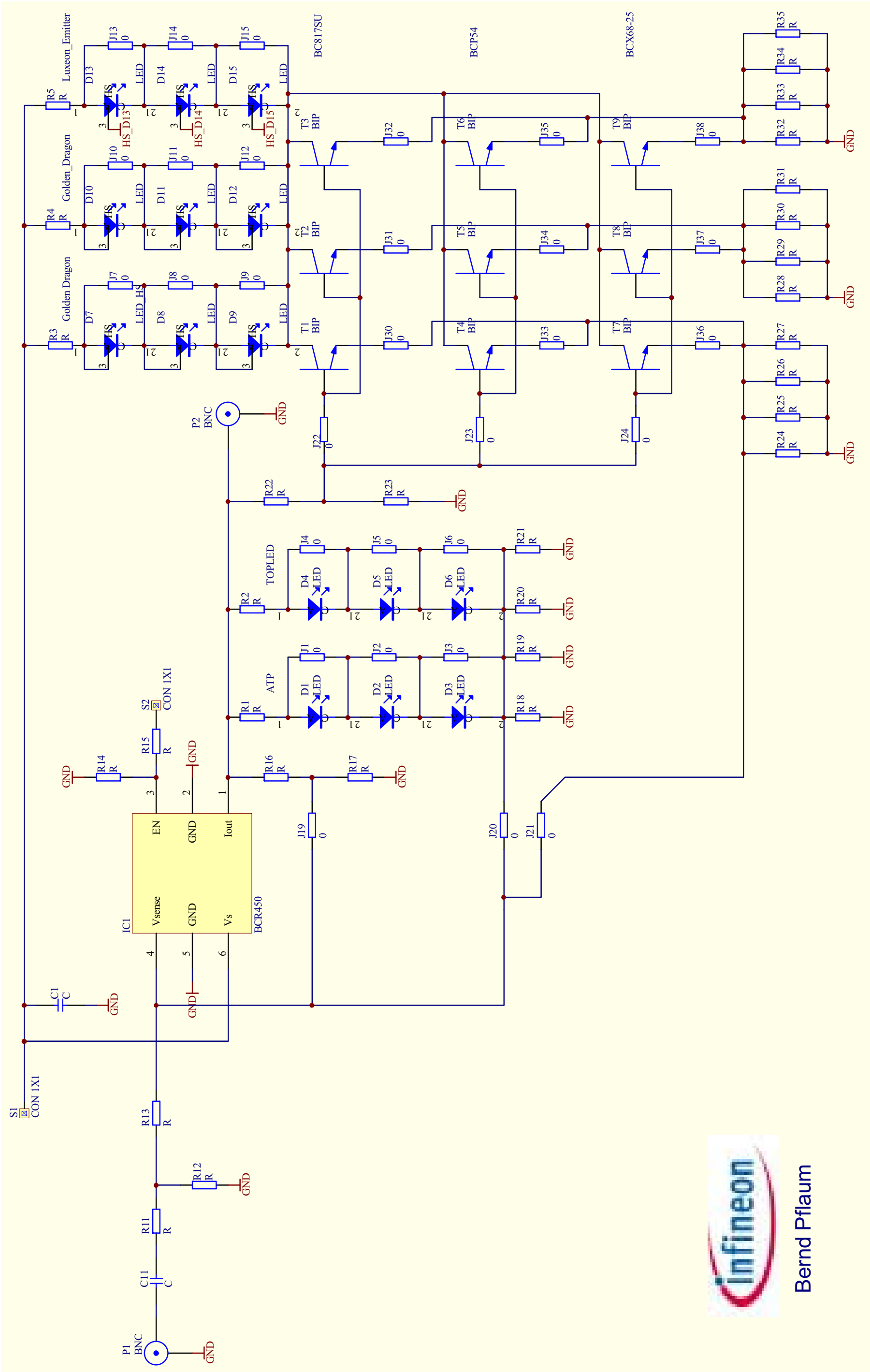


Figure 6 Detailed evaluation board schematic

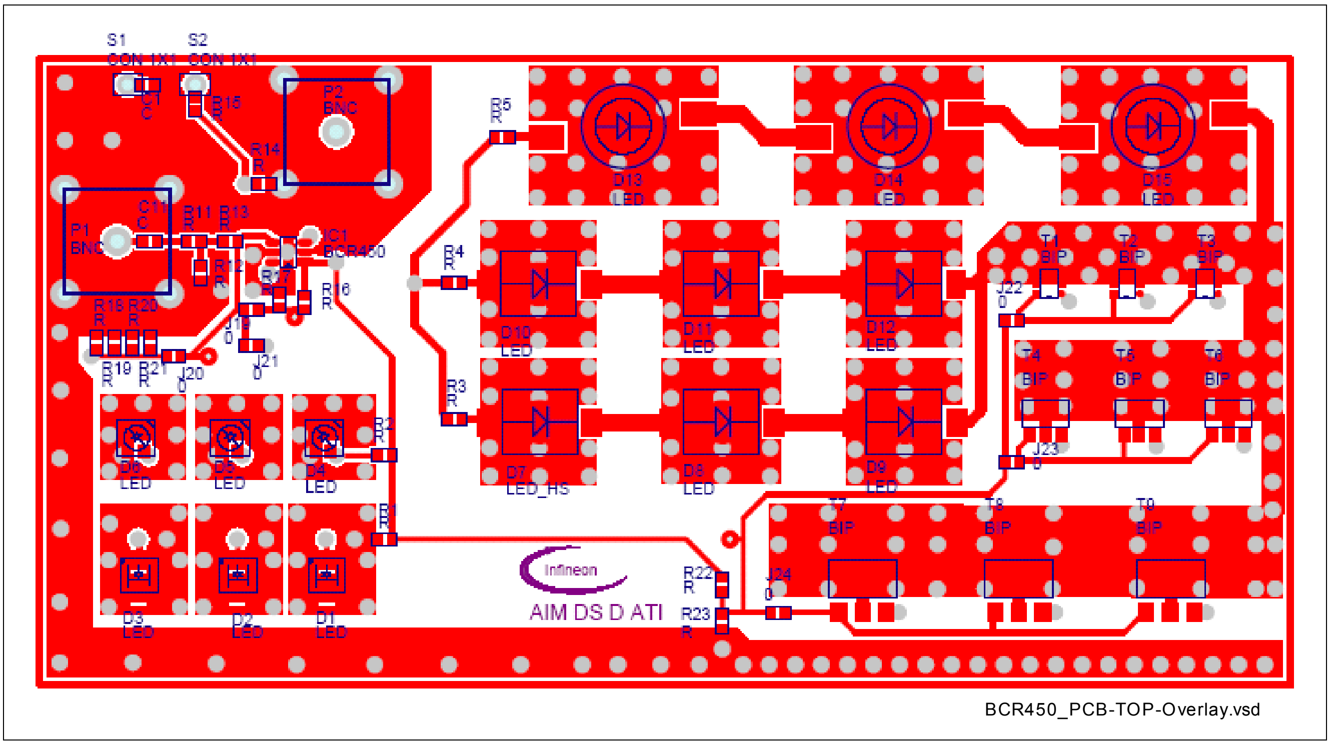


Figure 7 Top view on evaluation board (dimension 60 mm x 120 mm)

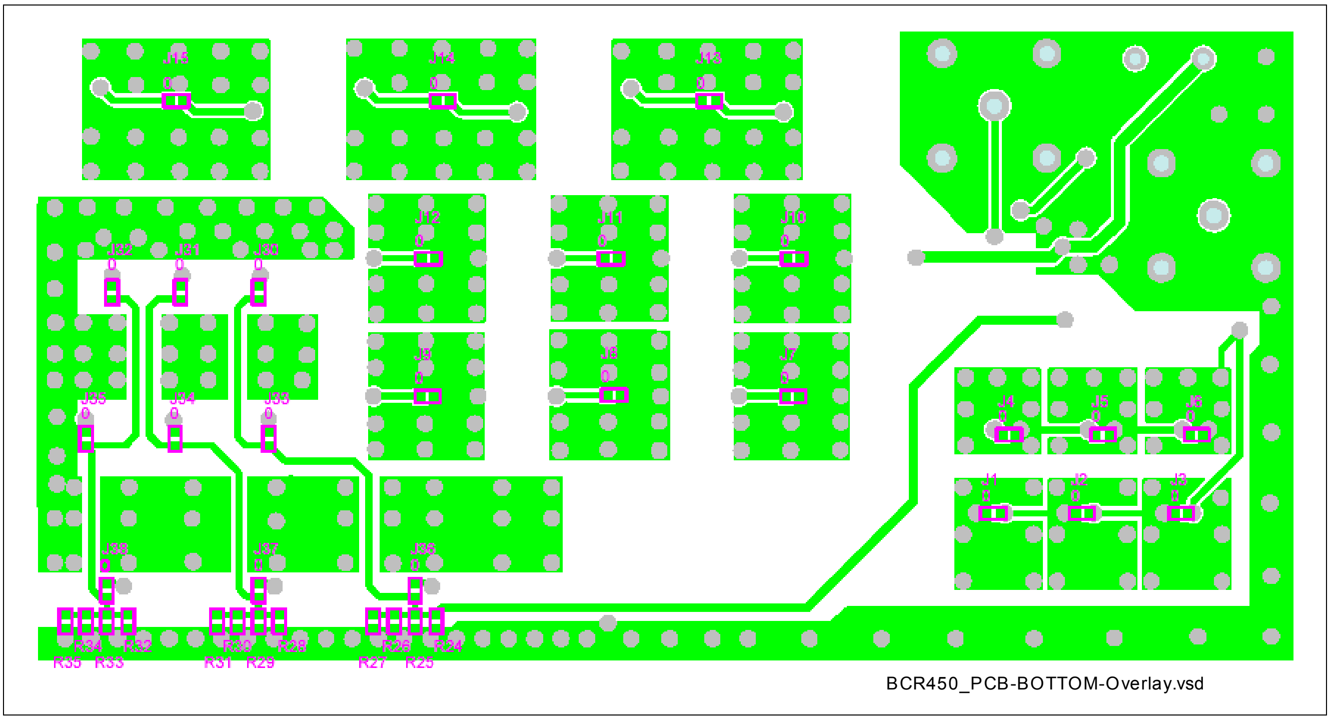


Figure 8 Bottom view on evaluation board (dimension 60 mm x 120 mm)

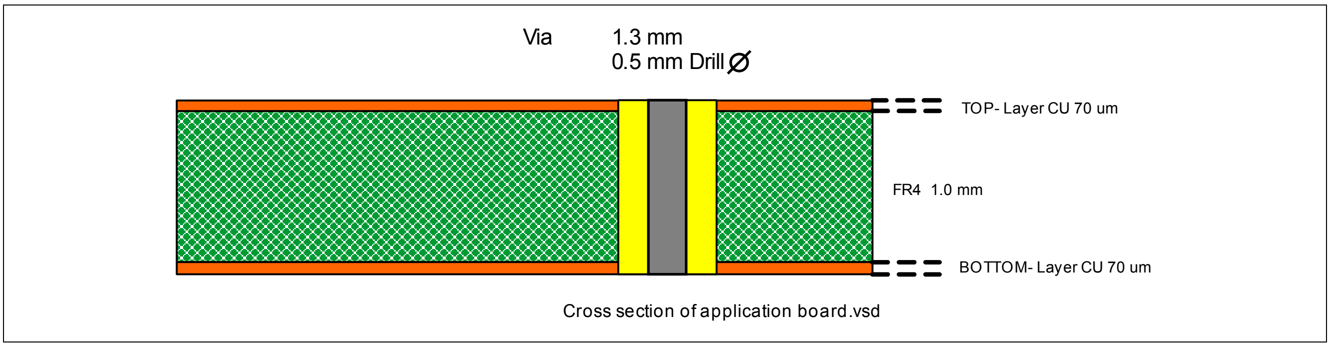


Figure 9 Cross section of evaluation board

6 Package Information

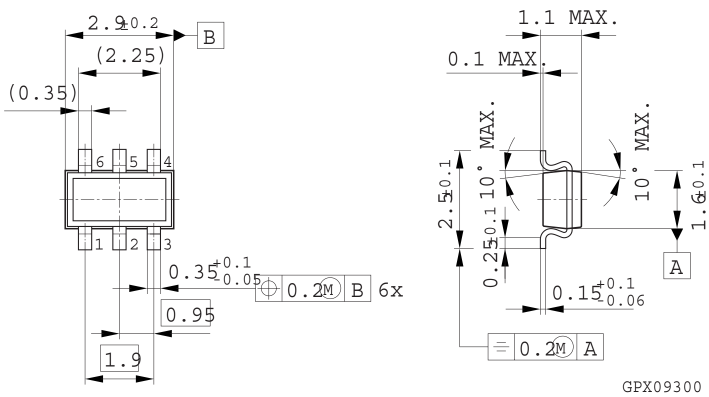


Figure 10 Package outline; TSOP6 / SC74

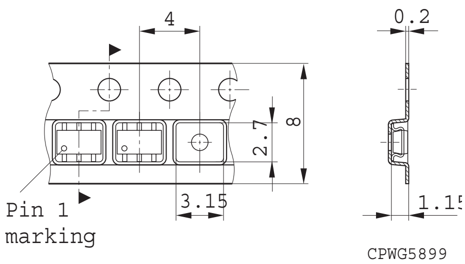


Figure 11 Tape loading